

M-20iD/12L



Max. load capacity
at wrist: 12 kg



Max. reach:
2272 mm

FANUC

| Robot | | | Max. load capacity at wrist (kg) | Reach (mm) | Controlled axes | Repeatability (mm) | Mechanical weight (kg) | Motion range (°) | | | | | | Maximum speed (°/s) | | | | | | Moments (N-m)/Inertia (kg-m ²) | | | Protection | | |
|--------|---------|------|----------------------------------|------------|-----------------|--------------------|------------------------|------------------|-----|-----|-----|-----|-----|---------------------|-----|-----|-----|-----|-----|--|--------------------|--------------------|--------------------------------|------------------------|----------------------------------|
| Series | Version | Type | | | | | | J1 | J2 | J3 | J4 | J5 | J6 | J1 | J2 | J3 | J4 | J5 | J6 | J4 Moment/ Inertia | J5 Moment/ Inertia | J6 Moment/ Inertia | Average Power consumption (kW) | Body standard/optional | Wrist & J3 arm standard/optional |
| M-20 | iD | 12L | 12 | 2272 | 6 | ±0.03** | 250 | 340 (370) | 260 | 458 | 400 | 360 | 900 | 210 | 210 | 265 | 420 | 450 | 720 | 22/.65 | 22/.65 | 9.8/.17 | 1 | IP54/ IP65 | IP67 |

● standard ○ on request - not available ** Based on ISO9283

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Long Arm, Hollow Wrist



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