

# M-410iB/140H



Max. load capacity  
at wrist: 140 kg



Max. reach:  
2850 mm

# FANUC

| Robot  |         |      | Max. load capacity at wrist (kg) | Reach (mm) | Controlled axes | Repeatability (mm) | Mechanical weight (kg) | Motion range (°) |     |     |    |     |    | Maximum speed (°/s) |     |     |     |     |    | J4 Moment/ Inertia | J5 Moment/ Inertia | J6 Moment/ Inertia | Average Power consumption (kW) | Protection             |                                  |
|--------|---------|------|----------------------------------|------------|-----------------|--------------------|------------------------|------------------|-----|-----|----|-----|----|---------------------|-----|-----|-----|-----|----|--------------------|--------------------|--------------------|--------------------------------|------------------------|----------------------------------|
| Series | Version | Type |                                  |            |                 |                    |                        | J1               | J2  | J3  | J4 | J5  | J6 | J1                  | J2  | J3  | J4  | J5  | J6 |                    |                    |                    |                                | Body standard/optional | Wrist & J3 arm standard/optional |
| M-410  | iB      | 140H | 140                              | 2850       | 5               | ± 0.05             | 1200                   | 360              | 155 | 112 | 20 | 720 | -  | 140                 | 115 | 135 | 135 | 420 | -  | 147                | 53                 | -                  | 3                              | IP54                   | IP54                             |

● standard ○ on request - not available \*\* Based on ISO9283

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5-axis



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