

LR Mate 200iD/4SH



Max. load capacity
at wrist: 4 kg



Max. reach:
550 mm

FANUC

| Robot | | | Max. load capacity at wrist (kg) | Reach (mm) | Controlled axes | Repeatability (mm) | Mechanical weight (kg) | Motion range (°) | | | | | | Maximum speed (°/s) | | | | | | J4 Moment/Inertia (Nm/kgm ²) | J5 Moment/Inertia (Nm/kgm ²) | J6 Moment/Inertia (Nm/kgm ²) | Average Power consumption (kW) | Protection | |
|-------------|---------|------|----------------------------------|------------|-----------------|--------------------|------------------------|------------------|-----|-----|-----|-----|----|---------------------|-----|-----|-----|------|----|--|--|--|--------------------------------|------------------------|----------------------------------|
| Series | Version | Type | | | | | | J1 | J2 | J3 | J4 | J5 | J6 | J1 | J2 | J3 | J4 | J5 | J6 | | | | | Body standard optional | Wrist & J3 arm standard/optional |
| LR Mate 200 | iD | 4SH | 4 | 550 | 5 | ±0.013** | 19 | 360 | 230 | 402 | 240 | 720 | - | 460 | 460 | 520 | 560 | 1500 | - | 8.86/0.2 | 4.0/0.046 | - | 0.5 | IP67 | IP67 |

● standard ○ on request - not available () with hardware and/or software option ** Based on ISO9283

LR Mate 200iD/4SH Short arm, 5-axis
(2 integrated solenoid valves)



LR Mate 200iD

